MATRA MHS

How to Get a Second Asynchronous Serial Interface on a 80C51 Microcontroller Family

Description

The 80C51 family has only one asynchronous serial interface.

However some users would like to have a low cost solution to get two in their applications.

This solution exists and is described in this application note.

The goal of this note is to present a very low cost software solution to realise this second asynchronous serial interface.

Features

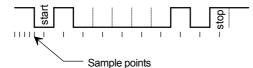
- No external hardware added ;
- Full duplex ;
- Dissymetrical baud rate in reception and in transmission available;
- 1200 bauds limitation of the internal serial interface (hardware).

Resources used

A time reference with interrupt capability is needed and it can be TIMER 1 even if it is already used as baud rate generator for the internal serial interface. In this case a 32 time speed transmission is obtained on TIMER 1 overflow (TIMER 1 is in mode 2 : 8-bit auto-reload, and serial interface is in mode 1 : 8-bit variable baud rate). Only two I/O pins are needed : one for RxD and one for TxD (for instance P1.0 and P1.1). Few bytes of memory are used and finally a portion of the CPU time is used to serve TIMER 1 interrupt. Three functions : initialisation, transmission and reception, are allowed to use this serial interface.

Method

Transmission of the character 01000001b 'A'



Receiver part :

On each TIMER 1 overflow interrupt, RxD input is sampled. Start of transmission is recognised by a transition of 1 to 0 on this pin. So a second sample is made half a bit later to be sure that it is a start bit. Then sampling is made in the middle of the received bits, nine times to get the 8 data bits. The stop bit must have level 1. Transmitter part :

The operation of the transmitter is nearly the same as for the receiver : start bit is written on TxD output followed by the 8 data bits and the stop bit and so on. Time of bit writing is calculated by counting timer interrupts.

Efficiency

Number of machine cycles spent in interrupt sub-routine :

- Minimum : 10 cycles ;
- Maximum : 49 cycles (transmission and reception);

The measures hereafter have been done with a 11.059MHz crystal, and same baud rate in emission and in reception, and a hardware serial baud rate of 1200 bauds.

Percentage of CPU usage :

- 41.7% if there is no traffic ;
- 50% with continuous transmission or reception, and 1200 baud rate ;
- 57.4% with continuous transmission and reception, and 1200 baud rate;
- 68.5% with continuous transmission and reception, and 9600 baud rate.

The hardware serial baud rate is limited to 1200 bauds, increasing it induces an increase of TIMER 1 interrupts frequency, and so an increase of percentage of CPU usage.

Demonstration Program

The demonstration program (listed in the following pages) allows transmission on P1.1 of all characters received on P1.0 without checking receive error.

The function TXD_S starts transmission of the character placed in accumulator when the transmitter is ready.

The function RXD_S waits for reception of a character and return it in accumulator.

Additional Information

For additional information on Microcontrollers, and Ordering Information, please refer to the following TEMIC/Matra MHS datasheets :

- 80C31/80C51
- 80C32/80C52
- 80C154/83C154
- 83C154D

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Program Listing

\$TITLE (Software serial interface) ; Software serial interface with programmable speed	; software serial interface demonstration program ; characters received on P1.0 are transmitted on P1.1			
\$NOMOD51 \$INCLUDE (reg51.inc)	RSEG PROG			
NAME UARTSOFT	; Main routine MAIN: mov SP,#STACK-1 lcall SEINIT ; interfaces init.			
; Constant definition RxD1 EQU P1.0 TxD1 EQU P1.1	LOOP: lcall RXD_S lcall TXD_S sjmp LOOP			
; Segment definition PROG SEGMENT CODE VAR1 SEGMENT DATA BITVAR SEGMENT BIT STACK SEGMENT IDATA	; Initialize serial interfaces ; desired speed is 32 for 1200 bauds, 4 for 9600 bauds ; Oscillator frequency = 11.059 MHz			
RSEG STACK DS 10H ; 16 Bytes Stack	SEINIT: mov TCON,#40H ; Timer 1 enabled mov TMOD,#20H ; C/T = 0, mode = 2			
; vectors definition CSEG AT 0000H ; Reset vector	mov TH1,#0E8H ; 1200 bauds mov SCON,#52H ; serial port mode 1			
jmp MAIN	mov A,#32 ; 1200 bauds mov RXSPD,A			
CSEG AT 001BH ; Timer 1 vector jmp ITIM1	mov TXSPD,A setb PT1 ; high priority It. setb TXRDY ; transmitter ready setb RXRDY ; receiver ready			
; bits definition RSEG BITVAR	clr RXERR ; no error mov IE,#10001000B ; It. timer 1 enabled			
TXRDY:DBIT 1; 1 if transmitter readyRXRDY:DBIT 1; 1 if receiver ready	ret			
RXERRDBIT 1; 1 if receiver errorINCOM:DBIT 1; 1 if character received	; Transmission of a character on TxD1 TXD_S: jnb TXRDY,TXD_S mov C,P mov ACC.7,C ; set parity			
; vars definition RSEG VAR1 ; Receiver	mov TXCH,A ; character to send mov A,TXSPD ; 1 bit duration rr A ; 1/2 bit duration			
RXSPD:DS 1; speed in receptionRXCH:DS 1; character in receptionRXCNT:DS 1; internal counterRXSTAT:DS 1; receiver status	mov TXCNT,A ; set counter mov TXSTAT,#0 ; init. status clr TXRDY ; start transmission ret			
RXCH2: DS 1 ; last character received	; Reading of the received character on RxD1			
; Transmitter TXSPD: DS 1 ; speed in transmission TXCH: DS 1 ; character in transmission TXCNT: DS 1 ; internal counter TXSTAT: DS 1 ; transmitter status	RXD_S: jnb INCOM,RXD_S mov A,RXCH2 ; char. received clr INCOM ; char. readed ret			

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; Interrupt : ITIM1:	routine jnb	RXRDY,RX1		TX2:	cjne setb	A,#10,TX3 TXRDY	; end of character ?
1111111		ver not busy			sjmp	TX4	
	jb clr	RxD1,TRANS RXRDY	; start bit ?	TX3:	setb mov	TxD1 TXCNT,TXSPE	; set stop bit
	push mov	ACC A,RXSPD	; 1 bit duration	TX4:	inc pop	TXSTAT PSW	
	rr	A	; $1/2$ bit duration	1711.	pop	ACC	
	mov	RXCNT,A	; load counter	TX5:	reti		
	mov	RXSTAT,#0	; init. status				
	pop	ACC			END		
RX1:	sjmp djnz	TRANS RXCNT TRAN	IS ; sample point ?				
	push	ACC	is, sample point :				
	push	PSW					
	mov	A,RXSTAT					
	jnz	RX3					
DV2.	jb	RXDI,ERRFRN RXSTAT	A; start bit OK (0)?				
RX2:	inc mov	RXCNT,RXSP	D				
	sjmp	RX5	D				
ERRFRM		RXRDY					
DV2.	setb	RXERR	; receiver error				
	sjmp	RX5	. 9 hita stan hit				
RX3:	cjne jnc	A,#9,\$+3 RX4	; 8 bits + stop bit				
	mov	C,RxD1	; bit sampling				
	mov	A,RXCH	,				
	rrc	A					
	mov	RXCH,A					
RX4:	sjmp jnb	RX2 RVD1 FRRFRN	A; stop bit OK (1)?				
	mov	RXCH2,RXCH					
	setb	RXRDY	-				
	setb	INCOM	; 1 char. received				
RX5:	pop	PSW					
	pop	ACC					
TRANS:		mission part					
	jb djnz	TXRDY,TX5 TXCNT,TX5	; sample point ?				
	push	ACC	, sample point ?				
	push	PSW					
	mov	A,TXSTAT					
	jnz	TX1	; start?				
	clr	TxD1 TYCNT TYSP	; set start bit				
	mov inc	TXCNT,TXSPI TXSTAT	D				
	sjmp	TX4					
TX1:	cjne	A,#9,\$+3	; 8 bits + stop bit				
	jnc	TX2					
	mov	A,TXCH	· hit to cond in com-				
	rrc mov	A TXCH,A	; bit to send in carry				
	mov	TxD1,C	; transmission of bit				
	mov	TXCNT,TXSPI	D; init. counter				
	inc	TXSTAT					
	sjmp	TX4					